

## ELECTROELASTIC ANALYSIS OF A PIEZOELECTRIC ELLIPTICAL INHOMOGENEITY

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**Abstract**—This paper is concerned with the development of a general solution for the elliptical inhomogeneity problem in piezoelectric materials under antiplane shear and inplane electric field. *Explicit* forms of the electroelastic fields are given in both the inhomogeneity and the matrix by means of the complex variable method. Furthermore, the change of the electric enthalpy due to the presence of an inhomogeneity is obtained. Numerical examples are provided to show the effect of the material mismatch, the aspect ratio of the inhomogeneity and the loading condition upon the change of the electric enthalpy and the electroelastic field concentration due to the presence of the inhomogeneity. © 1997 Elsevier Science Ltd.

### 1. INTRODUCTION

In view of their intrinsic electro-mechanical coupling characteristics and the potential for use in applications involving smart and adaptive material systems, piezoelectric ceramics are receiving increased attention from the scientific community. Electroelastic field concentrations at defects or inhomogeneities such as cracks, voids or particles in a piezoelectric composite material can contribute to critical crack growth and subsequent mechanical failure or dielectric breakdown. Therefore, it is of vital importance to study the electroelastic fields as a result of the presence of defects or inhomogeneities in these quasi-brittle solids.

Numerous attempts have been made to analyze a crack or a dislocation in piezoelectric materials, see for example the works of Barnett and Lothe (1975), McMeeking (1989), Pak (1990), Sosa and Pak (1990), Suo *et al.* (1992), Yang and Suo (1994), among others. Attempts have also been made to treat the inhomogeneity problem in this class of materials. Typical examples include the work of Deeg (1980) and Dunn and Taya (1993) who extended the application of the equivalent inclusion method of Eshelby (1957) to piezoelectric materials. More recently, Pak (1992) studied the antiplane problem of a piezoelectric circular inclusion, while Dunn (1994a) obtained the electroelastic field around an elliptical void or a flaw in a piezoelectric solid. Furthermore, Dunn (1994b) obtained the electroelastic Green's functions for transversely isotropic piezoelectric media. Liang *et al.* (1995) obtained the coupled electroelastic field inside the inhomogeneity and on the interface. In addition, Schulgasser (1992) and Chen (1993) established exact relations between the effective properties of piezoelectric composites. However, only a limited number of attempts have been made to explicitly determine the electroelastic field in the matrix, which is the subject of the current study.

In the present paper, we provide a general solution for the elliptical inhomogeneity problem in piezoelectric materials under antiplane shear and inplane electric field. Firstly, *explicit* forms of the electroelastic fields are given in both the inhomogeneity and the matrix by means of the complex variable method. Furthermore, the change of the electric enthalpy due to the presence of an inhomogeneity is obtained. Numerical examples are provided to examine the effect of the material mismatch, the aspect ratio of the inhomogeneity and the

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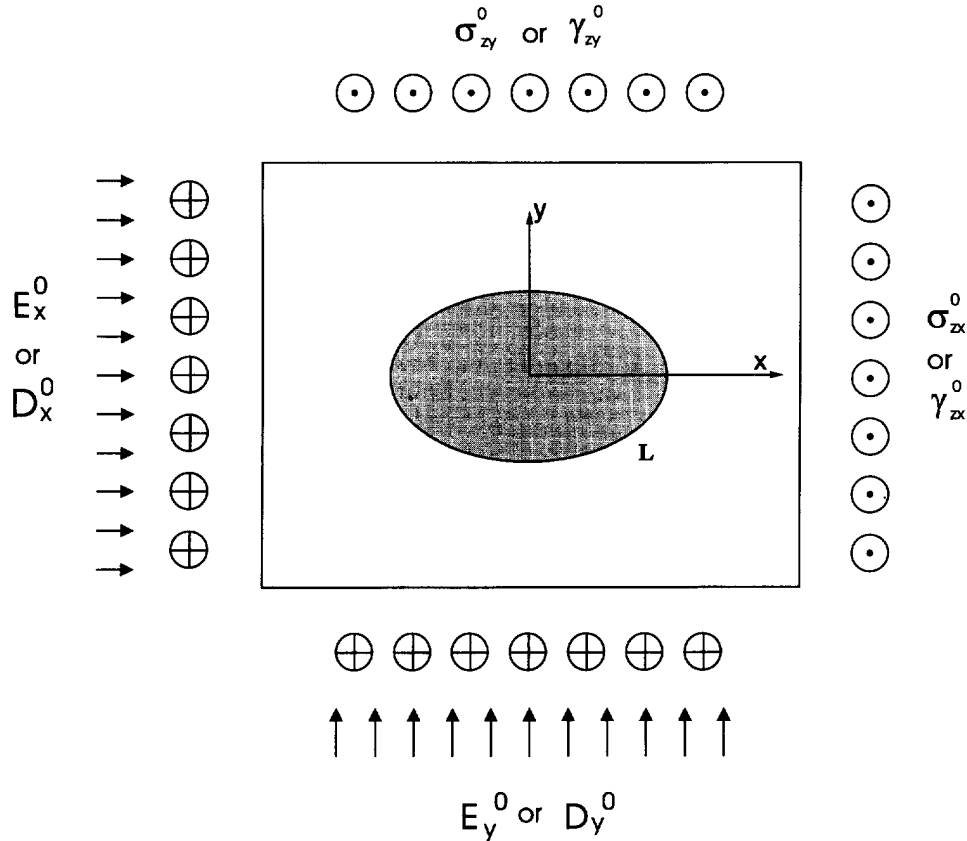


Fig. 1. A schematic of the elliptical piezoelectric inhomogeneity problem under consideration.

loading condition upon the change of the electric enthalpy and the electroelastic field concentration due to the presence of the inhomogeneity.

## 2. PROBLEM FORMULATION

Consider an elliptical piezoelectric inhomogeneity embedded in an unbounded piezoelectric matrix. The elliptical inhomogeneity, whose major and minor diameters are denoted by  $2a$  and  $2b$  (focal length  $c = (a^2 - b^2)^{1/2}$ ) is oriented with its major and minor axes along the  $x$  and  $y$  axes, respectively. The inhomogeneity and the matrix have different elastic and electric properties and are assumed to be transversely isotropic with respect to the longitudinal direction. The matrix is subjected to a remote inplane ( $x$ - $y$  plane) electric fields as well as out of plane shear, as shown in Fig. 1. The inhomogeneity is assumed to be perfectly bonded with the matrix at the interface  $L$ . The regions occupied by the matrix and the inhomogeneity will be referred to as regions 1 and 2, respectively. In addition, the quantities associated with the matrix and the inhomogeneity will be denoted by the corresponding superscripts or subscripts.

For this problem, the out-of-plane displacement  $w$  and the electric potential  $\phi$  are only functions of the variables  $x$  and  $y$ , such that  $w = w(x, y)$  and  $\phi = \phi(x, y)$ .

For linear piezoelectric materials, the electric enthalpy density can be expressed as (Pak, 1990)

$$h = \frac{1}{2} G_L (\gamma_{zx}^2 + \gamma_{zy}^2) - \frac{1}{2} k_{11} (E_x^2 + E_y^2) - e_{15} (\gamma_{zx} E_x + \gamma_{zy} E_y) \quad (1)$$

where  $\gamma_{zx}$  and  $\gamma_{zy}$  are the shear strains,  $E_x$  and  $E_y$  are the electric fields,  $G_L$  is the longitudinal shear modulus,  $e_{15}$  denotes the piezoelectric modulus and  $k_{11}$  represents the dielectric

modulus. The first term of eqn (1) is the energy stored in the deformation, the second term is the energy stored in the electric fields and the last terms is the interaction energy.

The equilibrium equations for the stresses and the electric displacements are

$$\begin{aligned}\frac{\partial \sigma_{zx}}{\partial x} + \frac{\partial \sigma_{zy}}{\partial y} &= 0 \\ \frac{\partial D_x}{\partial x} + \frac{\partial D_y}{\partial y} &= 0\end{aligned}\quad (2)$$

where  $\sigma_{zx}$  and  $\sigma_{zy}$  are the shear stresses, while  $D_x$  and  $D_y$  are the electric displacements.

The constitutive relations can be written as

$$\begin{aligned}\sigma_{zx} &= \frac{\partial h}{\partial \gamma_{zx}} = G_L \gamma_{zx} - e_{15} E_x \\ \sigma_{zy} &= \frac{\partial h}{\partial \gamma_{zy}} = G_L \gamma_{zy} - e_{15} E_y \\ D_x &= -\frac{\partial h}{\partial E_x} = e_{15} \gamma_{zx} + k_{11} E_x \\ D_y &= -\frac{\partial h}{\partial E_y} = e_{15} \gamma_{zy} + k_{11} E_y.\end{aligned}\quad (3)$$

The shear strains  $\gamma_{zx}$  and  $\gamma_{zy}$  and the electric fields  $E_x$  and  $E_y$  are related to the displacement  $w$  and the electric potential  $\phi$  by the following form:

$$\gamma_{zx} = \frac{\partial w}{\partial x} \quad \gamma_{zy} = \frac{\partial w}{\partial y} \quad E_x = -\frac{\partial \phi}{\partial x} \quad E_y = -\frac{\partial \phi}{\partial y}.\quad (4)$$

Substituting (3) and (4) into (2), we obtain the governing equations:

$$\nabla^2 w = 0 \quad \nabla^2 \phi = 0\quad (5)$$

where  $\nabla^2$  is the Laplacian operator.

Equation (5) indicates that  $w$  and  $\phi$  are harmonic functions which can be taken as the real part of some analytic functions of the complex variable  $z = x + iy$ , such that

$$\begin{aligned}w &= \frac{1}{2G_L}(\Psi(z) + \overline{\Psi(z)}) \\ \phi &= \frac{1}{2k_{11}}(\Phi(z) + \overline{\Phi(z)})\end{aligned}\quad (6)$$

where  $\Psi$  and  $\Phi$  represent the analytic functions and the overbar denotes the complex conjugate. Hence, the stresses and the electric displacements can be expressed as

$$\begin{aligned}\sigma_{zx} - i\sigma_{zy} &= \Psi'(z) + \frac{e_{15}}{k_{11}}\Phi'(z) \\ D_x - iD_y &= \frac{e_{15}}{G_L}\Psi'(z) - \Phi'(z)\end{aligned}\quad (7)$$

where the prime denotes the derivative with respect to the argument.

In order to define the continuity conditions at the inhomogeneity-matrix interface, we introduce two quantities:

$$\begin{aligned}
 T &= \int_A^B (\sigma_{zx} dy - \sigma_{zy} dx) \\
 &= \frac{i}{2} \left\{ [\overline{\Psi(z)} - \Psi(z)]_A^B + \frac{e_{15}}{k_{11}} [\overline{\Phi(z)} - \Phi(z)]_A^B \right\} \\
 S &= \int_A^B (D_x dy - D_y dx) \\
 &= \frac{i}{2} \left\{ \frac{e_{15}}{G_L} [\overline{\Psi(z)} - \Psi(z)]_A^B - [\overline{\Phi(z)} - \Phi(z)]_A^B \right\} \tag{8}
 \end{aligned}$$

where  $T$  is the resultant force along any arc  $AB$  and  $S$  is the sum of the normal component of the electric displacement along arc  $AB$ ;  $[\ ]_A^B$  denotes the change in the bracketed function in going from  $A$  to point  $B$  along the arc.

The assumption of perfect bonding between regions 1 and 2 implies that

$$w_1 = w_2 \quad \phi_1 = \phi_2 \quad T_1 = T_2 \quad B_1 = B_2 \quad \text{on } L. \tag{9}$$

### 3. SOLUTION

Using the approach of conformal transformation (see, e.g., Gong and Meguid, 1992, 1993), it can be shown that the complex potentials, which satisfy the governing eqn (5) and the boundary condition (9), have the following form :

$$\Psi_1(z) = (P_0^\bullet + iP_0^*)z + (K_0^\bullet + iK_0^*)[z - (z^2 - c^2)^{1/2}] \tag{10}$$

$$\Phi_1(z) = (Q_0^\bullet + iQ_0^*)z + (M_0^\bullet + iM_0^*)[z - (z^2 - c^2)^{1/2}] \tag{11}$$

in the matrix, and

$$\Psi_2(z) = (G_0^\bullet + iG_0^*)z \tag{12}$$

$$\Phi_2(z) = (H_0^\bullet + iH_0^*)z \tag{13}$$

in the inhomogeneity, where

$$\begin{Bmatrix} G_0^\bullet \\ G_0^* \end{Bmatrix} = (I_0^{(1)} \pm J_0^{(1)}) \begin{Bmatrix} P_0^\bullet \\ P_0^* \end{Bmatrix} + (L_0^{(1)} \pm N_0^{(1)}) \begin{Bmatrix} Q_0^\bullet \\ Q_0^* \end{Bmatrix} \tag{14}$$

$$\begin{Bmatrix} H_0^\bullet \\ H_0^* \end{Bmatrix} = (I_0^{(3)} \pm J_0^{(3)}) \begin{Bmatrix} P_0^\bullet \\ P_0^* \end{Bmatrix} + (L_0^{(3)} \pm N_0^{(3)}) \begin{Bmatrix} Q_0^\bullet \\ Q_0^* \end{Bmatrix} \tag{15}$$

$$\begin{Bmatrix} K_0^\bullet \\ K_0^* \end{Bmatrix} = \frac{1}{2} \left\{ [(I_0^{(2)} \pm J_0^{(2)})R^2 - 1] \begin{Bmatrix} P_0^\bullet \\ P_0^* \end{Bmatrix} + (L_0^{(2)} \pm N_0^{(2)})R^2 \begin{Bmatrix} Q_0^\bullet \\ Q_0^* \end{Bmatrix} \right\} \tag{16}$$

$$\begin{Bmatrix} M_0^\bullet \\ M_0^* \end{Bmatrix} = \frac{1}{2} \left\{ (I_0^{(4)} \pm J_0^{(4)})R^2 \begin{Bmatrix} P_0^\bullet \\ P_0^* \end{Bmatrix} + [(L_0^{(4)} \pm N_0^{(4)})R^2 - 1] \begin{Bmatrix} Q_0^\bullet \\ Q_0^* \end{Bmatrix} \right\} \tag{17}$$

with

$$R = \left(\frac{a+b}{a-b}\right)^{1/2} \tag{18}$$

and  $I_0^{(n)}, J_0^{(n)}, L_0^{(n)}$  and  $N_0^{(n)}$  ( $n = 1, 4$ ) are given in the Appendix. In these equations,  $P_0^\bullet, P_0^*, Q_0^\bullet$  and  $Q_0^*$  are real quantities, which will be determined from the far-field loading conditions. Substituting (10)–(13) into (6) and (7), we obtain the electroelastic fields, as follows:

$$w_1 = \frac{r}{G_L^1} \left[ (P_0^\bullet + K_0^\bullet) \cos \theta - (P_0^* + K_0^*) \sin \theta - \frac{\sqrt{r_1 r_2}}{r} K_0^\bullet \cos \left(\frac{\theta_1 + \theta_2}{2}\right) + \frac{\sqrt{r_1 r_2}}{r} K_0^* \sin \left(\frac{\theta_1 + \theta_2}{2}\right) \right] \tag{19}$$

$$\phi_1 = \frac{r}{k_{11}^1} \left[ (Q_0^\bullet + M_0^\bullet) \cos \theta - (Q_0^* + M_0^*) \sin \theta - \frac{\sqrt{r_1 r_2}}{r} M_0^\bullet \cos \left(\frac{\theta_1 + \theta_2}{2}\right) + \frac{\sqrt{r_1 r_2}}{r} M_0^* \sin \left(\frac{\theta_1 + \theta_2}{2}\right) \right] \tag{20}$$

$$\sigma_{zx1} = P_0^\bullet + K_0^\bullet + \frac{e_{15}^1}{k_{11}^1} (Q_0^\bullet + M_0^\bullet) - \left( K_0^\bullet + \frac{e_{15}^1}{k_{11}^1} M_0^\bullet \right) \frac{r}{\sqrt{r_1 r_2}} \cos \left(\theta - \frac{\theta_1 + \theta_2}{2}\right) + \left( K_0^* + \frac{e_{15}^1}{k_{11}^1} M_0^* \right) \frac{r}{\sqrt{r_1 r_2}} \sin \left(\theta - \frac{\theta_1 + \theta_2}{2}\right) \tag{21}$$

$$\sigma_{zy1} = -(P_0^* + K_0^*) - \frac{e_{15}^1}{k_{11}^1} (Q_0^* + M_0^*) + \left( K_0^\bullet + \frac{e_{15}^1}{k_{11}^1} M_0^\bullet \right) \frac{r}{\sqrt{r_1 r_2}} \sin \left(\theta - \frac{\theta_1 + \theta_2}{2}\right) + \left( K_0^* + \frac{e_{15}^1}{k_{11}^1} M_0^* \right) \frac{r}{\sqrt{r_1 r_2}} \cos \left(\theta - \frac{\theta_1 + \theta_2}{2}\right) \tag{22}$$

$$D_{x1} = \frac{e_{15}^1}{G_L^1} (P_0^\bullet + K_0^\bullet) - (Q_0^\bullet + M_0^\bullet) - \left( \frac{e_{15}^1}{G_L^1} K_0^\bullet - M_0^\bullet \right) \frac{r}{\sqrt{r_1 r_2}} \cos \left(\theta - \frac{\theta_1 + \theta_2}{2}\right) + \left( \frac{e_{15}^1}{G_L^1} K_0^* - M_0^* \right) \frac{r}{\sqrt{r_1 r_2}} \sin \left(\theta - \frac{\theta_1 + \theta_2}{2}\right) \tag{23}$$

$$D_{y1} = -\frac{e_{15}^1}{G_L^1} (P_0^* + K_0^*) + (Q_0^* + M_0^*) + \left( \frac{e_{15}^1}{G_L^1} K_0^\bullet - M_0^\bullet \right) \frac{r}{\sqrt{r_1 r_2}} \sin \left(\theta - \frac{\theta_1 + \theta_2}{2}\right) + \left( \frac{e_{15}^1}{G_L^1} K_0^* - M_0^* \right) \frac{r}{\sqrt{r_1 r_2}} \cos \left(\theta - \frac{\theta_1 + \theta_2}{2}\right) \tag{24}$$

the matrix, and

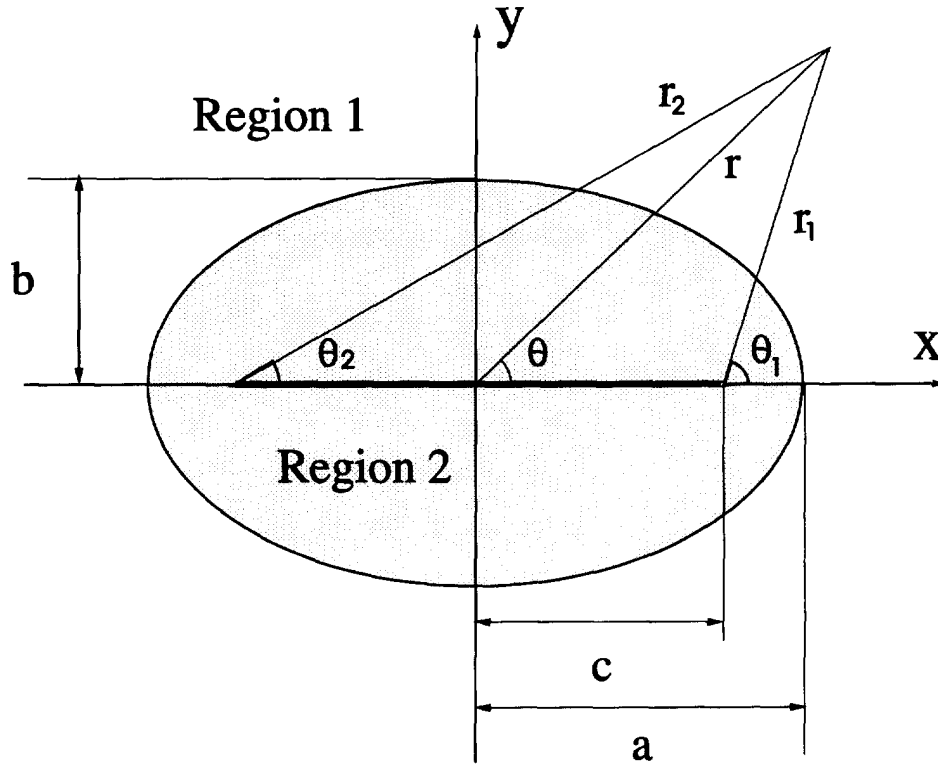


Fig. 2. A schematic of the coordinate used.

$$w_2 = \frac{r}{G_L^2} (G_0^\bullet \cos \theta - G_0^* \sin \theta) \quad (25)$$

$$\phi_2 = \frac{r}{k_{11}^2} (H_0^\bullet \cos \theta - H_0^* \sin \theta) \quad (26)$$

$$\sigma_{zx2} = G_0^\bullet + \frac{e_{15}^2}{k_{11}^2} H_0^\bullet \quad (27)$$

$$\sigma_{zy2} = -G_0^* - \frac{e_{15}^2}{k_{11}^2} H_0^* \quad (28)$$

$$D_{x2} = \frac{e_{15}^2}{G_L^2} G_0^\bullet - H_0^\bullet \quad (29)$$

$$D_{y2} = -\frac{e_{15}^2}{G_L^2} G_0^* + H_0^* \quad (30)$$

in the inhomogeneity, where  $r$  and  $\theta$  are defined in Fig. 2. By applying the far-field loading conditions (Pak, 1990),  $P_0^\bullet$ ,  $P_0^*$ ,  $Q_0^\bullet$  and  $Q_0^*$  are evaluated as follows:

Case 1: the matrix is subjected to uniform strains  $\gamma_{zx}^0$  and  $\gamma_{zy}^0$  as well as uniform electric fields  $E_x^0$  and  $E_y^0$  at infinity. In this case, we have

$$P_0^\bullet = G_L^1 \gamma_{zx}^0 \quad (31)$$

$$P_0^* = -G_L^1 \gamma_{zy}^0 \quad (32)$$

$$Q_0^\bullet = -k_{11}^1 E_x^0 \quad (33)$$

$$Q_0^* = k_{11}^1 E_y^0. \quad (34)$$

Case 2: the matrix is subjected to uniform stresses  $\sigma_{zx}^0$  and  $\sigma_{zy}^0$ , as well as uniform electric displacements  $D_x^0$  and  $D_y^0$  at infinity. In this case, we can determine

$$P_0^\bullet = \frac{G_L^1(k_{11}^1 \sigma_{zx}^0 + e_{15}^1 D_x^0)}{G_L^1 k_{11}^1 + (e_{15}^1)^2} \quad (35)$$

$$P_0^* = -\frac{G_L^1(k_{11}^1 \sigma_{zy}^0 + e_{15}^1 D_y^0)}{G_L^1 k_{11}^1 + (e_{15}^1)^2} \quad (36)$$

$$Q_0^\bullet = \frac{k_{11}^1 (e_{15}^1 \sigma_{zx}^0 - G_L^1 D_x^0)}{G_L^1 k_{11}^1 + (e_{15}^1)^2} \quad (37)$$

$$Q_0^* = -\frac{k_{11}^1 (e_{15}^1 \sigma_{zy}^0 - G_L^1 D_y^0)}{G_L^1 k_{11}^1 + (e_{15}^1)^2}. \quad (38)$$

Case 3: the matrix is subjected to uniform strains  $\gamma_{zx}^0$  and  $\gamma_{zy}^0$ , as well as uniform electric displacements  $D_x^0$  and  $D_y^0$  at infinity. In this case, we obtain

$$P_0^\bullet = G_L^1 \gamma_{zx}^0 \quad (39)$$

$$P_0^* = -G_L^1 \gamma_{zy}^0 \quad (40)$$

$$Q_0^\bullet = e_{15}^1 \gamma_{zx}^0 - D_x^0 \quad (41)$$

$$Q_0^* = -e_{15}^1 \gamma_{zy}^0 + D_y^0. \quad (42)$$

Case 4: the matrix is subjected to uniform stresses  $\sigma_{zx}^0$  and  $\sigma_{zy}^0$ , as well as uniform electric fields  $D_x^0$  and  $D_y^0$  at infinity. In this case, we can find

$$P_0^\bullet = \sigma_{zx}^0 + e_{15}^1 E_x^0 \quad (43)$$

$$P_0^* = -\sigma_{zy}^0 - e_{15}^1 E_y^0 \quad (44)$$

$$Q_0^\bullet = -k_{11}^1 E_x^0 \quad (45)$$

$$Q_0^* = k_{11}^1 E_y^0. \quad (46)$$

It can be observed from (27)–(30) that the stress and electric fields are constant within the elliptical inhomogeneity which confirms the results of Wang (1992), Benveniste (1992) and Dunn (1994). The main contribution of the present solution is in its ability to determine the electroelastic field in the matrix explicitly. In fact, our solution reduces to the earlier results of Pak for the special case of a circular inhomogeneity (Pak, 1992) and an elliptical void (Pak, 1990).

Another interesting aspect of the present solution is the ability to determine the change of the total electric enthalpy in the body due to the introduction of an inhomogeneity. The total electric enthalpy  $H$  in a piezoelectric solid of unit thickness and cross-sectional area  $D$  can be written as

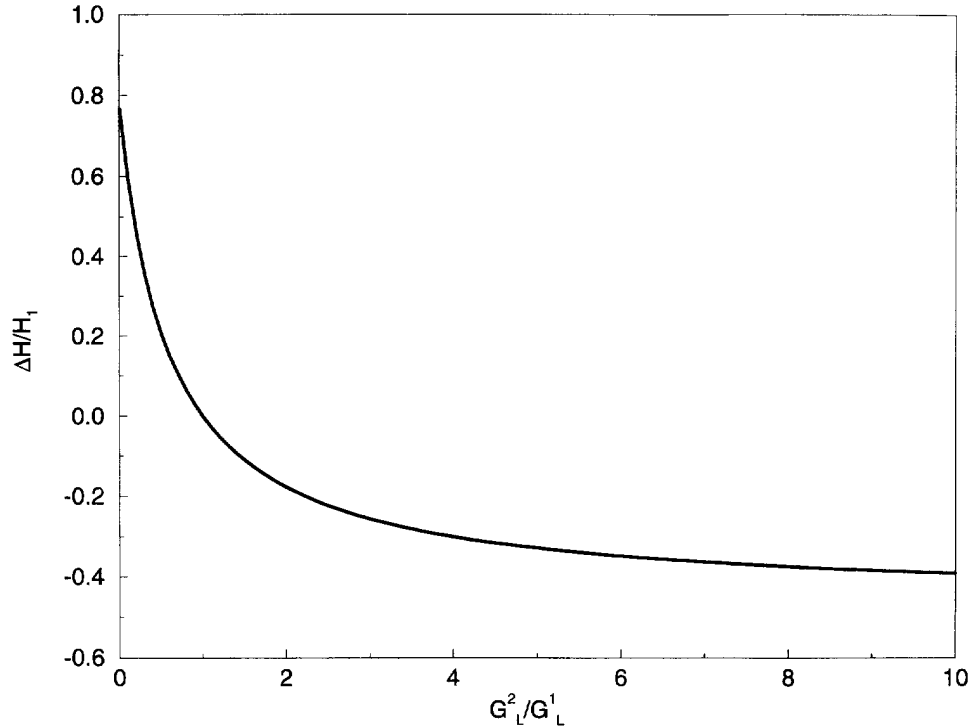


Fig. 3. Variations of the normalized electric enthalpy  $\Delta H/H_1$  vs the shear moduli ratio  $G_L^2/G_L^1$ .

$$H = \iint_D h \, ds \quad (47)$$

where  $h$  is the electric enthalpy density given by (1). It can be shown that

$$H = H_0 + \Delta H \quad (48)$$

where  $H_0$  is the electric enthalpy in the absence of inhomogeneities and  $\Delta H$  represents the contribution due to the introduction of an inhomogeneity. Following the approach used by Gong and Meguid (1992, 1993),  $\Delta H$  can be evaluated as

$$\Delta H = \frac{\pi e^2}{2} \left[ \frac{1}{G_L^1} (P_0^\bullet K_0^\bullet - P_0^* K_0^*) - \frac{1}{k_{11}^1} (Q_0^\bullet M_0^\bullet - Q_0^* M_0^*) + \frac{e_{15}^1}{G_L^1 k_{11}^1} (P_0^\bullet M_0^\bullet + Q_0^\bullet K_0^\bullet - P_0^* M_0^* - Q_0^* K_0^*) \right] \quad (49)$$

#### 4. NUMERICAL RESULTS AND DISCUSSION

In this section, we examine the effect of the material mismatch between the inhomogeneity and the matrix, the aspect ratio of the inhomogeneity and the loading condition upon the change of the electric enthalpy and the electroelastic field concentrations due to the presence of the inhomogeneity.

As an example, let us consider an elliptical inhomogeneity with an aspect ratio  $a/b = 3$ , embedded in an infinite matrix subjected to remote uniform stress and electric field, such that:  $\sigma_{zy}^0 = 5 \times 10^7 \text{ N/m}^2$ ,  $\sigma_{zx}^0 = 0$ ,  $E_y^0 = 10^6 \text{ V/m}$  and  $E_x^0 = 0$ .

Figure 3 shows the variation of the normalized electric enthalpy  $\Delta H/H_1$  vs shear moduli ratio  $G_L^2/G_L^1$ . The inhomogeneity and the matrix are assumed to have the same dielectric and piezoelectric moduli:  $k_{11}^1 = k_{11}^2 = 1.51 \times 10^{-8} \text{ C/Vm}$ ,  $e_{15}^1 = e_{15}^2 = 10.0 \text{ C/m}^2$  and



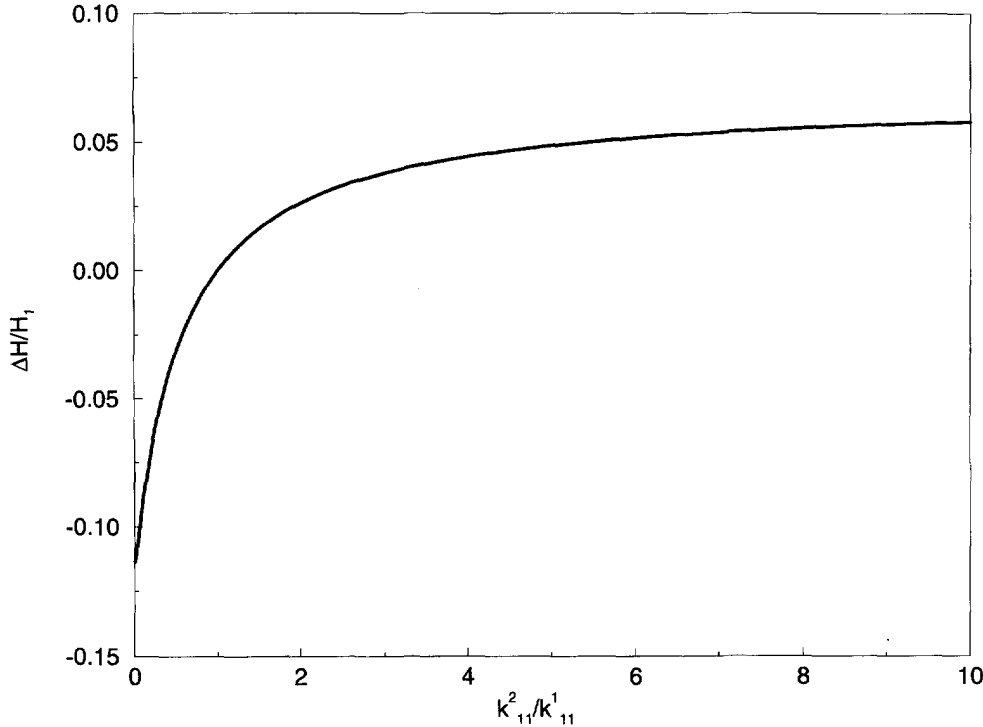


Fig. 4. Variations of the normalized electric enthalpy  $\Delta H/H_1$  vs the dielectric moduli ratio  $k_{11}^2/k_{11}^1$ .

$G_L^1 = 3.53 \times 10^{10}$  N/m<sup>2</sup>.  $H_1$  is an energy factor used to normalize the electric enthalpy and is given by:

$$H_1 = \frac{\pi a^2}{G_L^1} [(P_0^\bullet)^2 + (P_0^*)^2] + \frac{\pi a^2}{k_{11}^1} [(Q_0^\bullet)^2 + (Q_0^*)^2]. \quad (50)$$

It is observed from Fig. 3 that an increase in  $G_L^2/G_L^1$  results in a sharp decline in  $\Delta H$  when the inhomogeneity is softer than the matrix ( $G_L^2/G_L^1 < 1$ ). In the case where the inhomogeneity is harder ( $G_L^2/G_L^1 > 1$ ), the decline is rather gradual approaching asymptotically the case of a rigid inhomogeneity. The figure also reveals that for  $G_L^2/G_L^1 \geq 5$ , the elastic inhomogeneity can be treated as a rigid body.

Figure 4 shows the variation of the normalized electric enthalpy  $\Delta H/H_1$  vs the dielectric moduli ratio  $k_{11}^2/k_{11}^1$ . The inhomogeneity and the matrix are assumed to have the same shear and piezoelectric moduli:  $G_L^1 = 3.53 \times 10^{10}$  N/m<sup>2</sup>,  $e_{15}^1 = e_{15}^2 = 10.0$  C/m<sup>2</sup> and  $k_{11}^1 = 1.51 \times 10^{-8}$  C/Vm. It is observed that with the increase of  $k_{11}^2/k_{11}^1$ ,  $\Delta H$  increases sharply when the dielectric modulus of the inhomogeneity is less than that of the matrix, but increases gradually approaching asymptotically the case of a conducting inhomogeneity when the dielectric modulus of the inhomogeneity is greater than that of the matrix. The figure also reveals that for  $k_{11}^2/k_{11}^1 \geq 5$ , the dielectric inhomogeneity can be treated as a conductor.

Figure 5 shows the variation of the normalized electric enthalpy  $\Delta H/H_1$  vs the piezoelectric moduli ratio  $e_{15}^2/e_{15}^1$ . The inhomogeneity and the matrix are assumed to have the same shear and dielectric moduli:  $G_L^1 = G_L^2 = 3.53 \times 10^{10}$  N/m<sup>2</sup>,  $k_{11}^1 = k_{11}^2 = 1.51 \times 10^{-8}$  C/Vm and  $e_{15}^1 = 10.0$  C/m<sup>2</sup>. It can be observed from this figure that  $\Delta H/H_1$  experiences a sudden jump from  $-0.46$  at  $e_{15}^2/e_{15}^1 = -3.0$  to  $0.08$  at  $e_{15}^2/e_{15}^1 = 3.0$ . This jump is caused by the mismatch of the piezoelectric moduli between the inhomogeneity and the matrix.

Figure 6 shows the variation of the normalized electric enthalpy  $\Delta H/H_1$  vs the aspect ratio of the elliptical inhomogeneity for different ratios of shear moduli. The inhomogeneity and the matrix have the following material constants:  $G_L^1 = 3.53 \times 10^{10}$  N/m<sup>2</sup>,  $k_{11}^1 = k_{11}^2 = 1.51 \times 10^{-8}$  C/Vm,  $e_{15}^1 = 10.0$  C/m<sup>2</sup> and  $e_{15}^2 = 0$ . It can be observed that  $\Delta H$

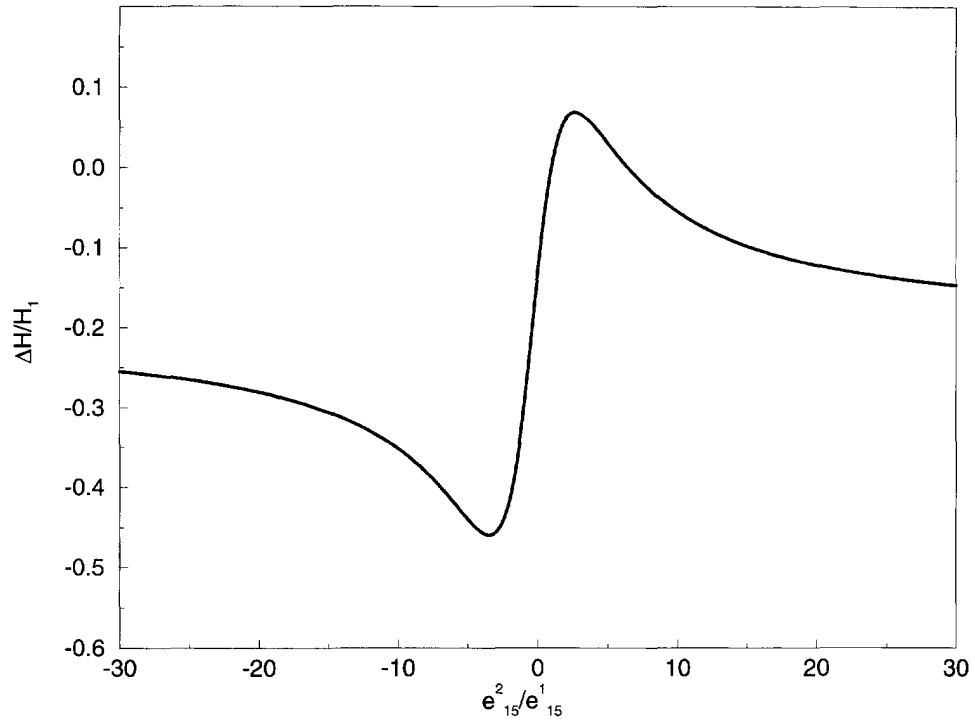


Fig. 5. Variations of the normalized electric enthalpy  $\Delta H/H_1$  vs the piezoelectric moduli ratio  $e_{15}^2/e_{15}^1$ .

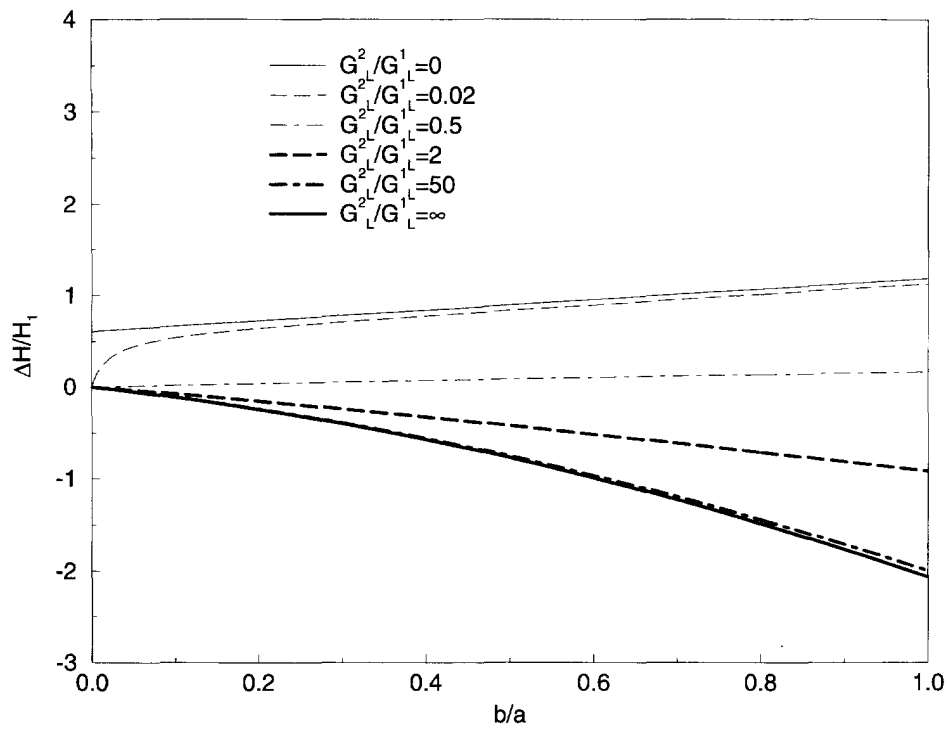


Fig. 6. Variations of the normalized electric enthalpy  $\Delta H/H_1$  vs the aspect ratio  $b/a$  of the inhomogeneity.

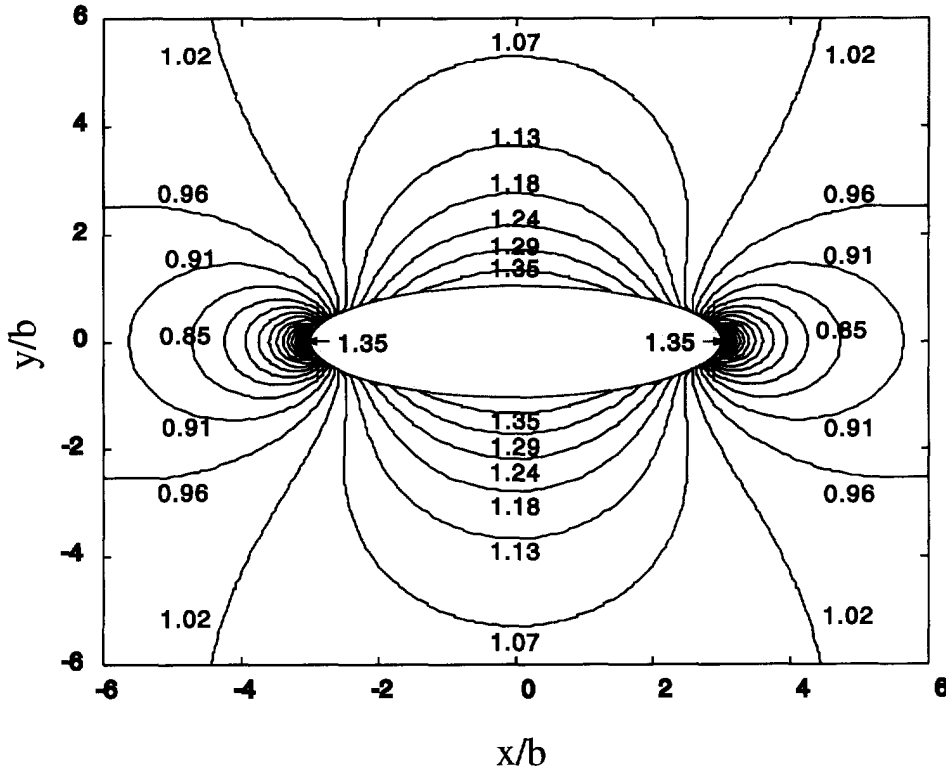


Fig. 7. Contours of constant shear stress ratio  $\sigma_{xy}/\sigma_{xy}^0$  for the case where  $\sigma_{zy}^0 = 5 \times 10^7 \text{ N/m}^2$ ,  $\sigma_{zx}^0 = 0$ ,  $E_x^0 = 10^6 \text{ V/m}$  and  $E_y^0 = 0$ .

increases with the increase of the aspect ratio  $b/a$  when the inhomogeneity is softer than the matrix, but decreases with the increase of  $b/a$  when the inhomogeneity is harder. This figure also shows two limiting cases: the first is concerned with a void ( $G_L^2/G_L^1 = 0$ ) and the second with a rigid inhomogeneity ( $G_L^2/G_L^1 = \infty$ ).

Finally, Figs 7 and 8 show the strong dependence of the electroelastic field upon the far-field loading. Figure 7 shows contours of constant shear stress ratio  $\sigma_{xy}/\sigma_{xy}^0$  due to a remote applied load of  $\sigma_{zx}^0 = 0$ ,  $\sigma_{zy}^0 = 5 \times 10^7 \text{ N/m}^2$ ,  $E_x^0 = 0$  and  $E_y^0 = 10^6 \text{ V/m}$ . Figure 8 shows contours of  $\sigma_{xy}/\sigma_{xy}^0$  for the case where  $\sigma_{zx}^0 = 5 \times 10^7 \text{ N/m}^2$ ,  $\sigma_{zy}^0 = 0$ ,  $E_x^0 = 10^6 \text{ V/m}$  and  $E_y^0 = 0$  for the same material system. From these figures one can observe the difference between contours of the shear stress as a result of the externally applied mechanical and electric loads. Although severe concentrations are observed near the interface, along the minor radius of the inhomogeneity in both cases, the contour shape in these two figures is quite different. For example,  $\sigma_{xy}$  is symmetric about the  $x$ - and  $y$ -axes as depicted in Fig. 7, while anti-symmetric about the origin as shown in Fig. 8.

### 5. CONCLUDING REMARKS

A general solution is provided for the elliptical inhomogeneity problem in piezoelectric materials under antiplane shear and inplane electric field. The explicit forms of the electroelastic fields in both the inhomogeneity and the matrix are obtained using the complex variable method. A convenient form of the change of the electric enthalpy due to the presence of an inhomogeneity was also obtained. The electroelastic field concentrations and the change of electric enthalpy were evaluated for different test cases and were found to be strongly dependent upon the material mismatch, the aspect ratio of the inhomogeneity and the remote loading condition. Specifically, the results show that an elastic inhomogeneity can be treated as a rigid body when the shear moduli ratio  $G_L^2/G_L^1 \geq 5$  and a dielectric inhomogeneity can be treated as a conductor when the dielectric moduli ratio  $k_{11}^2/k_{11}^1 \geq 5$ . They also reveal that the electric enthalpy increases with increasing aspect

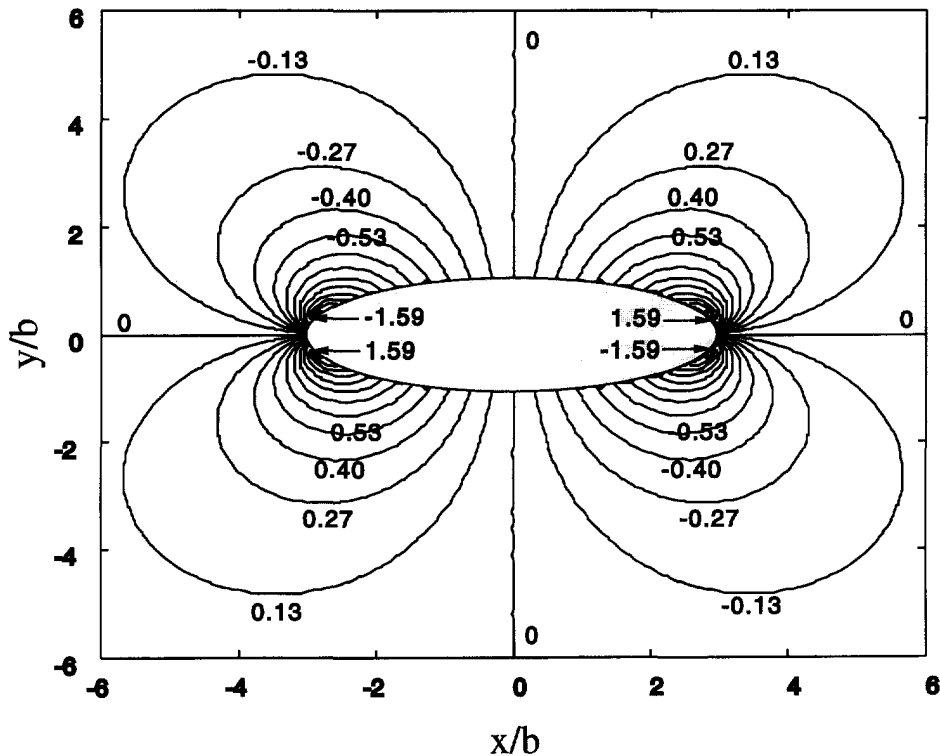


Fig. 8. Contours of constant shear stress ratio  $\sigma_{xy}/\sigma_{x1}^0$  for the case where  $\sigma_{x1}^0 = 0$ ,  $\sigma_{x2}^0 = 5 \times 10^7$  N/m<sup>2</sup>,  $E_y^0 = 0$  and  $E_x^0 = 10^6$  V/m.

ratio of a relatively softer inhomogeneity ( $G_L^2/G_L^1 < 1$ ) and decreases with a harder inhomogeneity ( $G_L^2/G_L^1 > 1$ ).

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## APPENDIX

$$I_0^{(1)} = \lambda_1 + \lambda_3 \quad (\text{A1.1})$$

$$J_0^{(1)} = \lambda_1 + \lambda_3 \quad (\text{A1.2})$$

$$L_0^{(1)} = \lambda_2 + \lambda_4 \quad (\text{A1.3})$$

$$N_0^{(1)} = \lambda_2 + \lambda_4 \quad (\text{A1.4})$$

$$I_0^{(3)} = \lambda_5 + \lambda_7 \quad (\text{A1.5})$$

$$J_0^{(3)} = \lambda_5 + \lambda_7 \quad (\text{A1.6})$$

$$L_0^{(3)} = \lambda_6 + \lambda_8 \quad (\text{A1.7})$$

$$N_0^{(3)} = \lambda_6 + \lambda_8 \quad (\text{A1.8})$$

$$I_0^{(2)} = \frac{1}{\mu_1} \left( \lambda_1 - \lambda_3 + \frac{\lambda_1 + \lambda_3}{R^2} \right) \quad (\text{A1.9})$$

$$J_0^{(2)} = \frac{1}{\mu_1} \left( \lambda_1 + \lambda_3 + \frac{\lambda_1 - \lambda_3}{R^2} \right) - 1 \quad (\text{A1.10})$$

$$L_0^{(2)} = \frac{1}{\mu_1} \left( \lambda_2 - \lambda_4 + \frac{\lambda_2 + \lambda_4}{R^2} \right) \quad (\text{A1.11})$$

$$N_0^{(2)} = \frac{1}{\mu_1} \left( \lambda_2 + \lambda_4 + \frac{\lambda_2 - \lambda_4}{R^2} \right) \quad (\text{A1.12})$$

$$I_0^{(4)} = \frac{1}{\mu_2} \left( \lambda_5 - \lambda_7 + \frac{\lambda_5 + \lambda_7}{R^2} \right) \quad (\text{A1.13})$$

$$J_0^{(4)} = \frac{1}{\mu_2} \left( \lambda_5 + \lambda_7 + \frac{\lambda_5 - \lambda_7}{R^2} \right) \quad (\text{A1.14})$$

$$L_0^{(4)} = \frac{1}{\mu_2} \left( \lambda_6 - \lambda_8 + \frac{\lambda_6 + \lambda_8}{R^2} \right) \quad (\text{A1.15})$$

$$N_0^{(4)} = \frac{1}{\mu_2} \left( \lambda_6 + \lambda_8 + \frac{\lambda_6 - \lambda_8}{R^2} \right) - 1 \quad (\text{A1.16})$$

with

$$\lambda_1 = \frac{1}{\delta_1} \left\{ \left[ \left( 1 + \frac{1}{\mu_2} \right) - \left( 1 - \frac{1}{\mu_2} \right) \frac{1}{R^2} \right] + \frac{e_{15}^1}{G_l k_{11}^2} \left[ (e_{15}^1 + e_{15}^2) + (e_{15}^1 - e_{15}^2) \frac{1}{R^2} \right] \right\} \quad (\text{A1.17})$$

$$\lambda_2 = \frac{1}{\delta_1} \left\{ \frac{e_{15}^1}{k_{11}^1} \left[ \left( 1 + \frac{1}{\mu_2} \right) - \left( 1 - \frac{1}{\mu_2} \right) \frac{1}{R^2} \right] - \frac{1}{k_{11}^2} \left[ (e_{15}^1 + e_{15}^2) + (e_{15}^1 - e_{15}^2) \frac{1}{R^2} \right] \right\} \quad (\text{A1.18})$$

$$\lambda_3 = \frac{1}{\delta_2} \left\{ \left[ \left( 1 + \frac{1}{\mu_2} \right) + \left( 1 - \frac{1}{\mu_2} \right) \frac{1}{R^2} \right] + \frac{e_{15}^1}{G_L^1 k_{11}^2} \left[ (e_{15}^1 + e_{15}^2) - (e_{15}^1 - e_{15}^2) \frac{1}{R^2} \right] \right\} \quad (\text{A1.19})$$

$$\lambda_4 = \frac{1}{\delta_2} \left\{ \frac{e_{15}^1}{k_{11}^1} \left[ \left( 1 + \frac{1}{\mu_2} \right) + \left( 1 - \frac{1}{\mu_2} \right) \frac{1}{R^2} \right] - \frac{1}{k_{11}^2} \left[ (e_{15}^1 + e_{15}^2) - (e_{15}^1 - e_{15}^2) \frac{1}{R^2} \right] \right\} \quad (\text{A1.20})$$

$$\lambda_5 = -\frac{1}{\delta_1} \left\{ \frac{e_{15}^1}{G_L^1} \left[ \left( 1 + \frac{1}{\mu_1} \right) - \left( 1 - \frac{1}{\mu_1} \right) \frac{1}{R^2} \right] - \frac{1}{G_L^2} \left[ (e_{15}^1 + e_{15}^2) + (e_{15}^1 - e_{15}^2) \frac{1}{R^2} \right] \right\} \quad (\text{A1.21})$$

$$\lambda_6 = \frac{1}{\delta_1} \left\{ \left[ \left( 1 + \frac{1}{\mu_1} \right) - \left( 1 - \frac{1}{\mu_1} \right) \frac{1}{R^2} \right] + \frac{e_{15}^1}{G_L^2 k_{11}^1} \left[ (e_{15}^1 + e_{15}^2) + (e_{15}^1 - e_{15}^2) \frac{1}{R^2} \right] \right\} \quad (\text{A1.22})$$

$$\lambda_7 = -\frac{1}{\delta_2} \left\{ \frac{e_{15}^1}{G_L^1} \left[ \left( 1 + \frac{1}{\mu_1} \right) + \left( 1 - \frac{1}{\mu_1} \right) \frac{1}{R^2} \right] - \frac{1}{G_L^2} \left[ (e_{15}^1 + e_{15}^2) - (e_{15}^1 - e_{15}^2) \frac{1}{R^2} \right] \right\} \quad (\text{A1.23})$$

$$\lambda_8 = \frac{1}{\delta_2} \left\{ \left[ \left( 1 + \frac{1}{\mu_1} \right) + \left( 1 - \frac{1}{\mu_1} \right) \frac{1}{R^2} \right] + \frac{e_{15}^1}{G_L^2 k_{11}^1} \left[ (e_{15}^1 + e_{15}^2) - (e_{15}^1 - e_{15}^2) \frac{1}{R^2} \right] \right\} \quad (\text{A1.24})$$

$$\delta_1 = \left[ \left( 1 + \frac{1}{\mu_1} \right) - \left( 1 - \frac{1}{\mu_1} \right) \frac{1}{R^2} \right] \left[ \left( 1 + \frac{1}{\mu_2} \right) - \left( 1 - \frac{1}{\mu_2} \right) \frac{1}{R^2} \right] + \frac{1}{G_L^2 k_{11}^2} \left[ (e_{15}^1 + e_{15}^2) - (e_{15}^1 - e_{15}^2) \frac{1}{R^2} \right]^2 \quad (\text{A1.25})$$

$$\delta_2 = \left[ \left( 1 + \frac{1}{\mu_1} \right) + \left( 1 - \frac{1}{\mu_1} \right) \frac{1}{R^2} \right] \left[ \left( 1 + \frac{1}{\mu_2} \right) + \left( 1 - \frac{1}{\mu_2} \right) \frac{1}{R^2} \right] + \frac{1}{G_L^2 k_{11}^2} \left[ (e_{15}^1 + e_{15}^2) - (e_{15}^1 - e_{15}^2) \frac{1}{R^2} \right]^2. \quad (\text{A1.26})$$